

# Unified LTL Verification and Embedded Execution of UML Models

*ACM/IEEE 21<sup>th</sup> International Conference on Model Driven Engineering  
Languages and Systems (MODELS '18) in Copenhagen, Denmark*

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This work has been partially  
funded by Davidson.



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# Context

## Observations

- Increasing complexity of embedded systems
- Emergence of new needs and applications
- Connection of these systems to networks (IoT)

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- More safety and security requirements

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- Increasing complexity of embedded systems
- Emergence of new needs and applications
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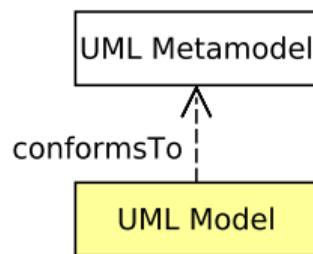
## Consequences on software programs

- More prone to uncertain behaviors, security flaws, and design mistakes
- More safety and security requirements

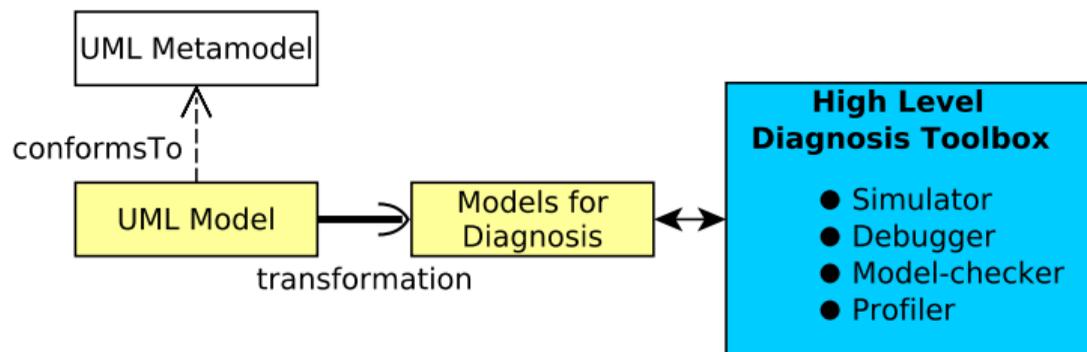
## Consequence on software development

- Increasing need of verification and validation

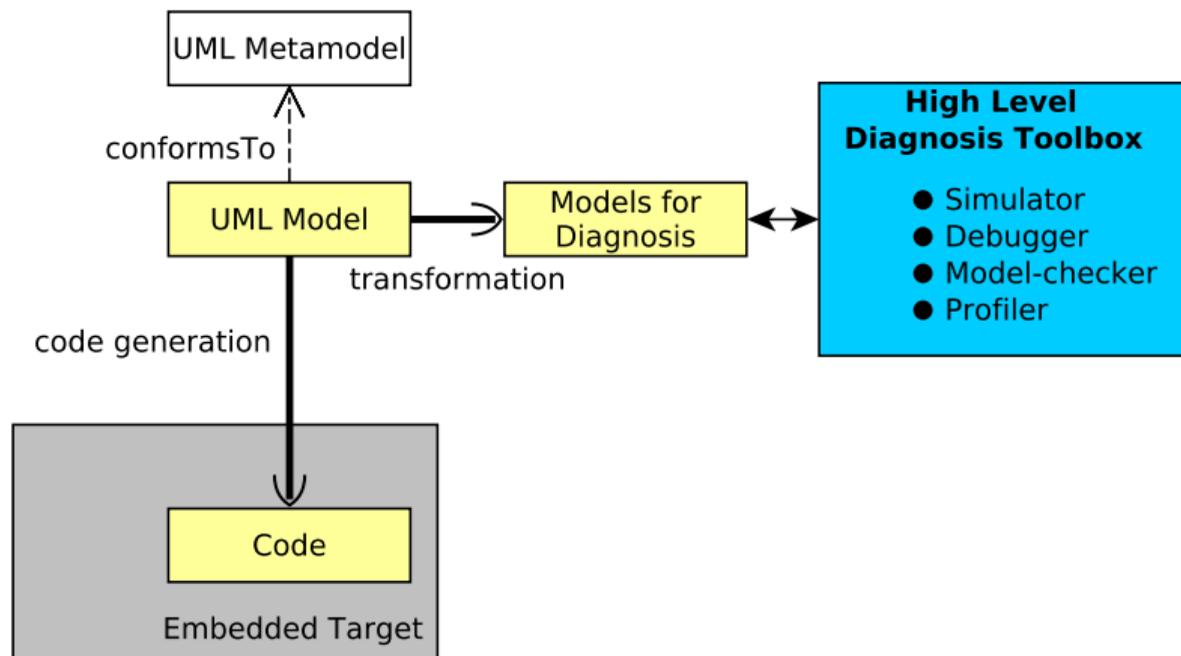
# Classical UML-based Approaches



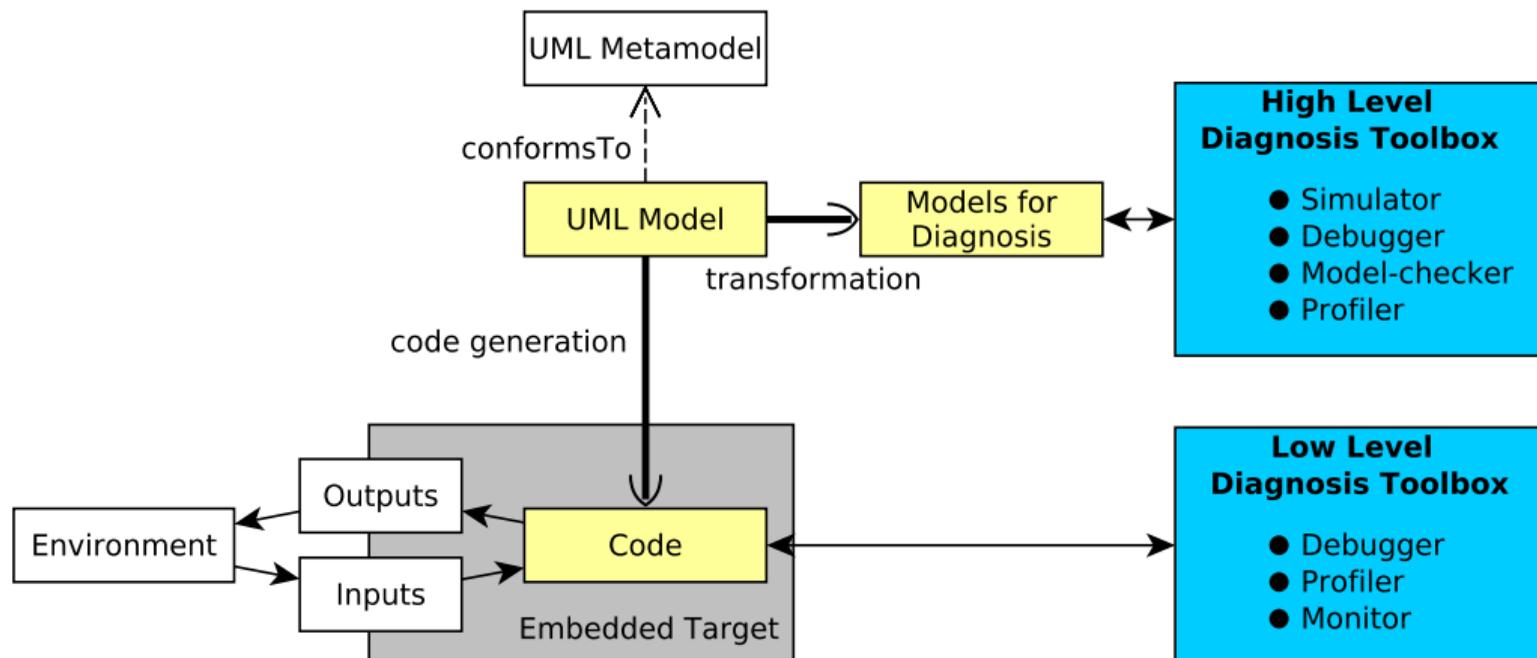
# Classical UML-based Approaches



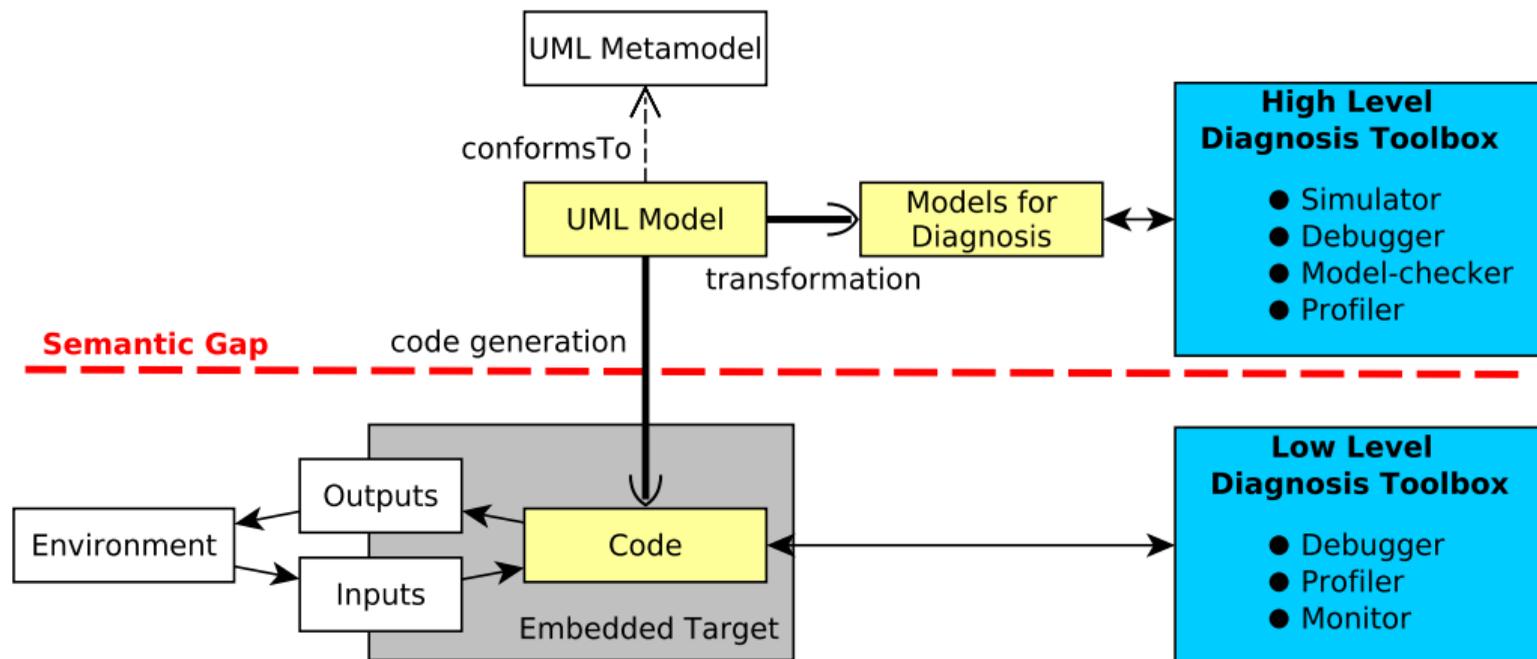
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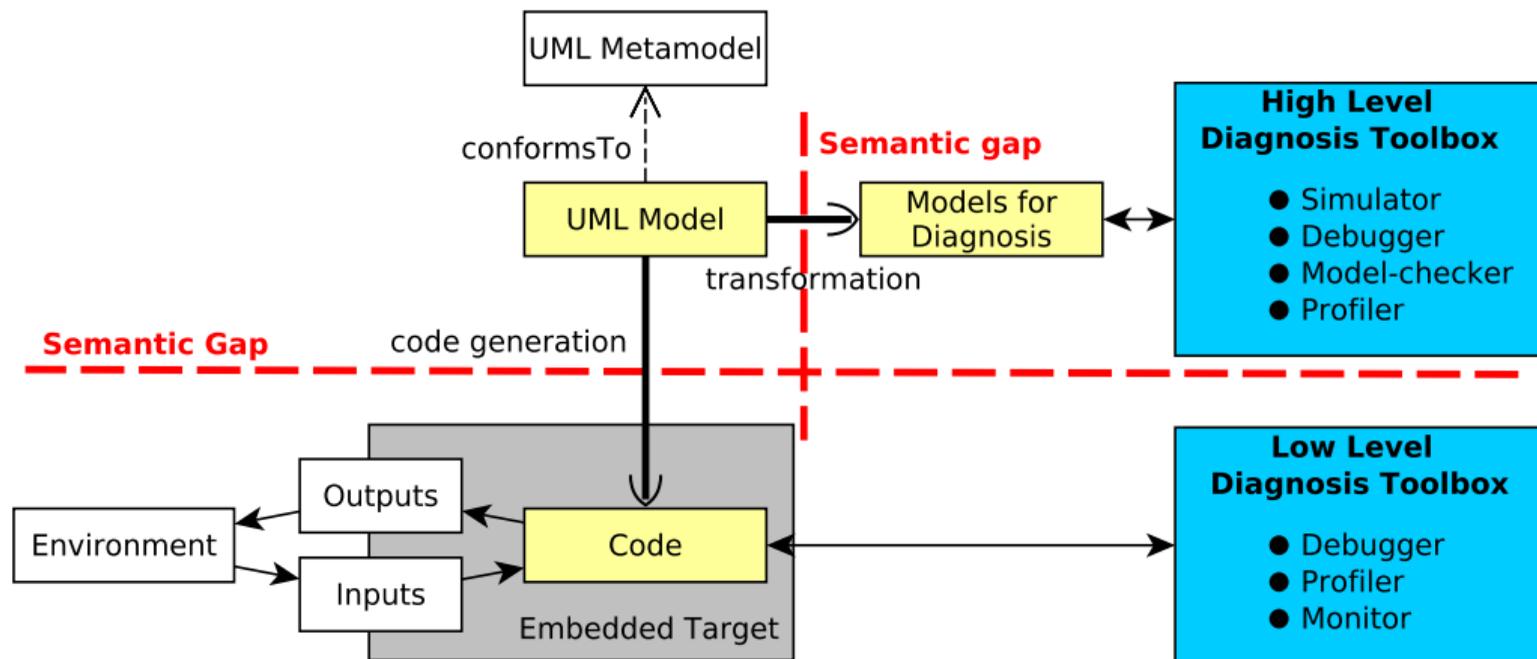


## Some Problems



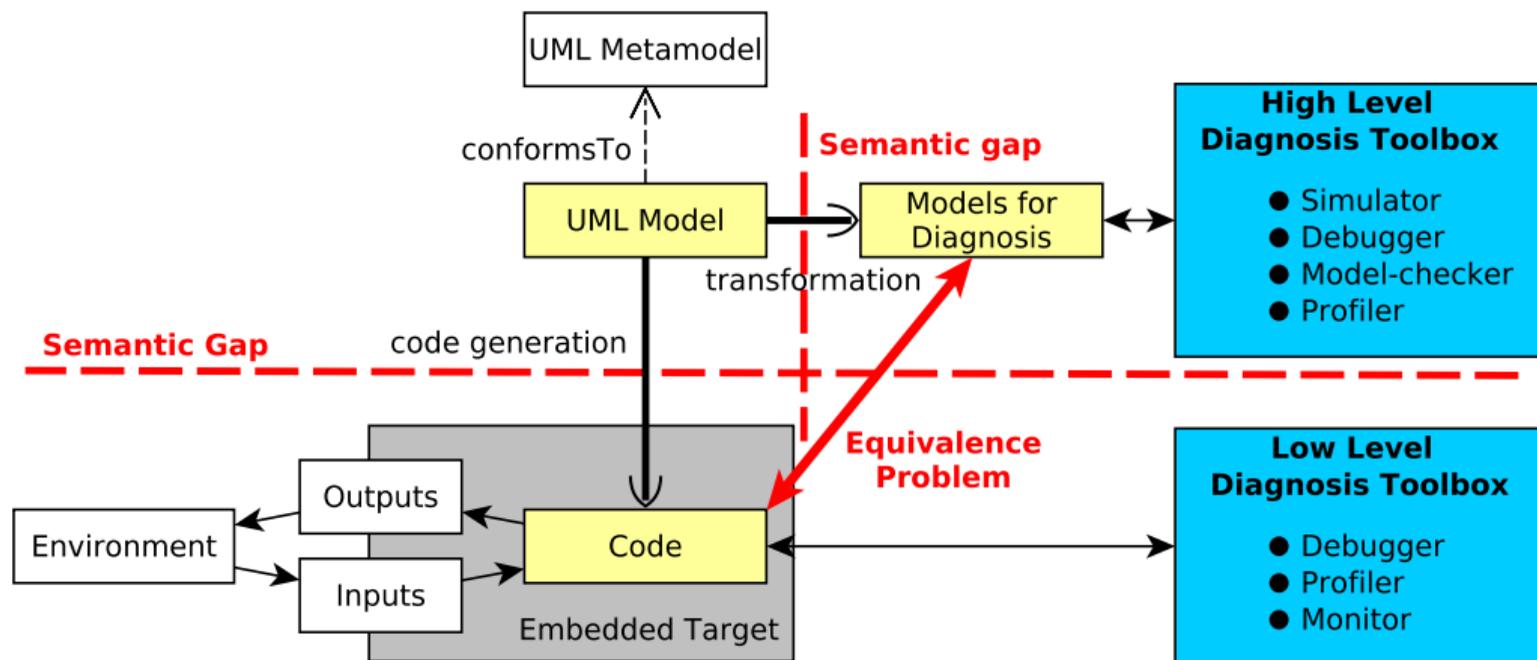
**First issue:** Semantic gap between design model and executable code.

## Some Problems



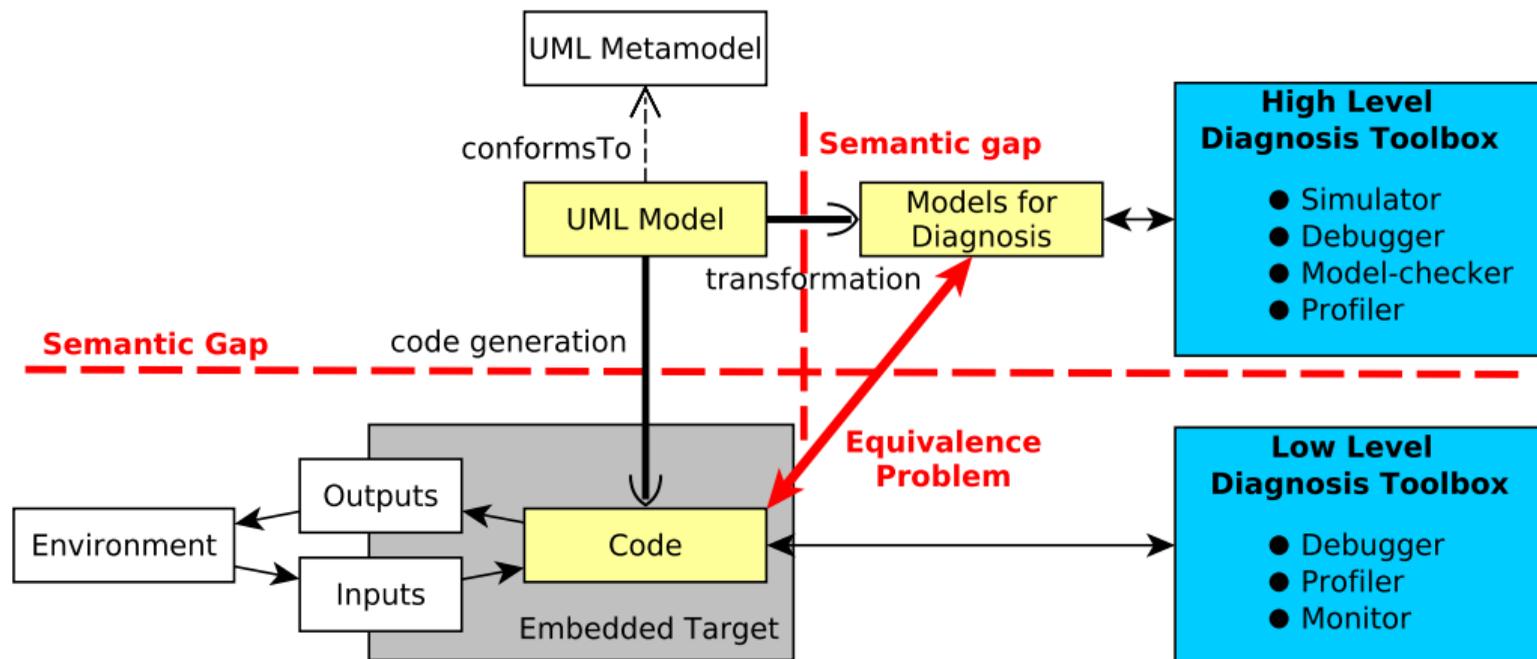
**Second issue:** Semantic gap between design model and diagnosis model.

## Some Problems



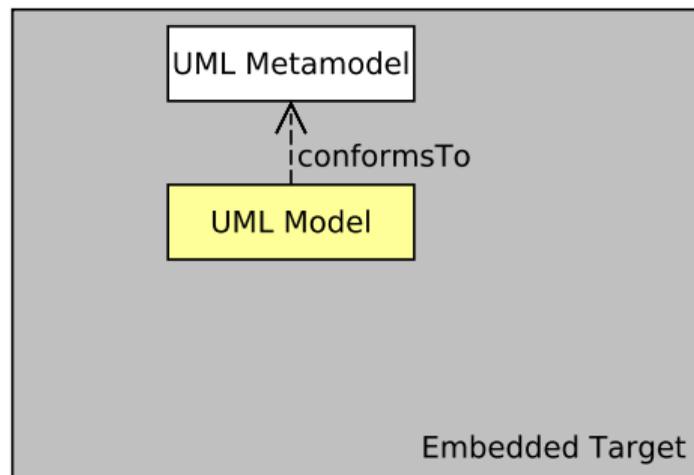
**Third issue:** An equivalence relation between verified formal models and deployed code should be built, proven, and maintained.

## Some Problems

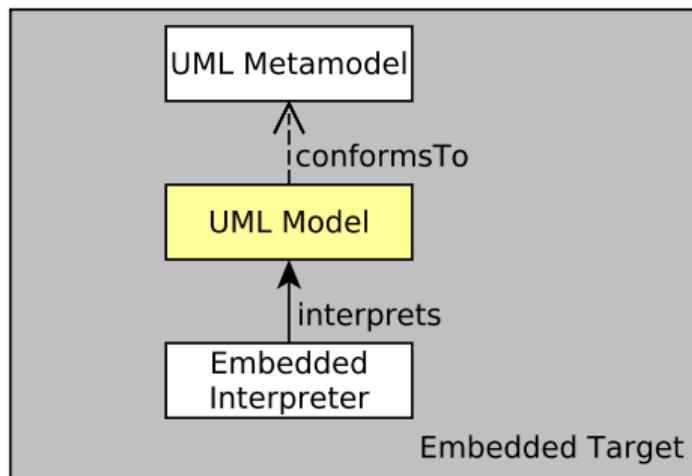


Main cause of these problems: Multiple definitions of the modeling language semantics.

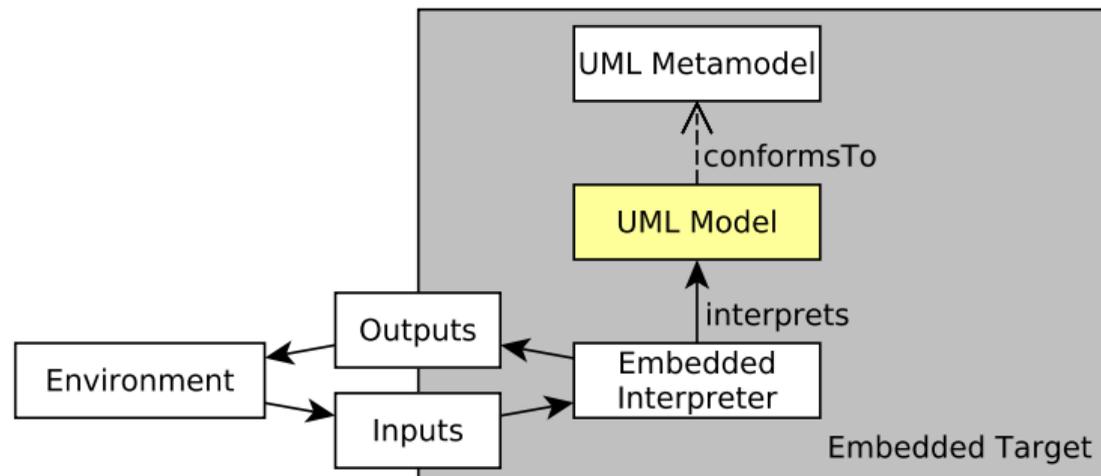
# Our Approach: A Unified Modeling Language Semantics



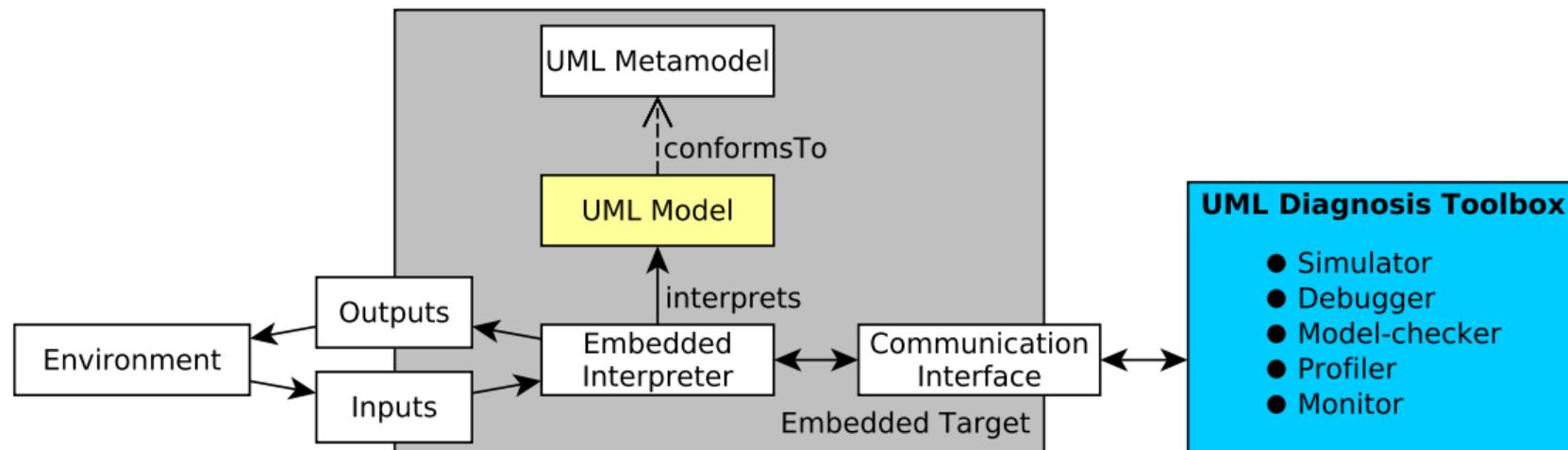
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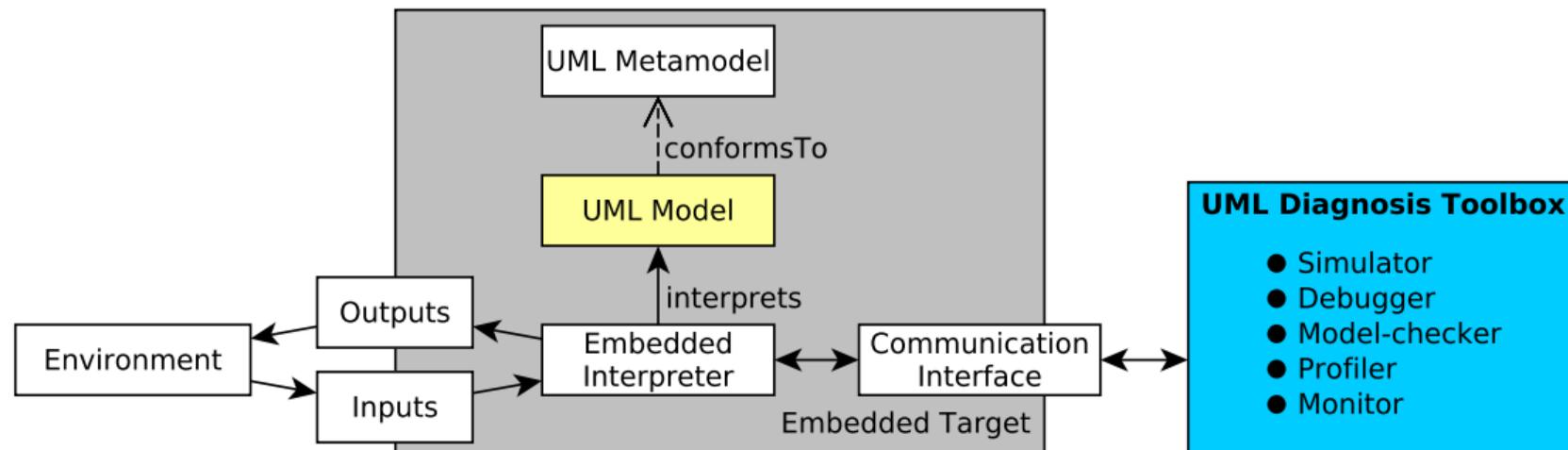
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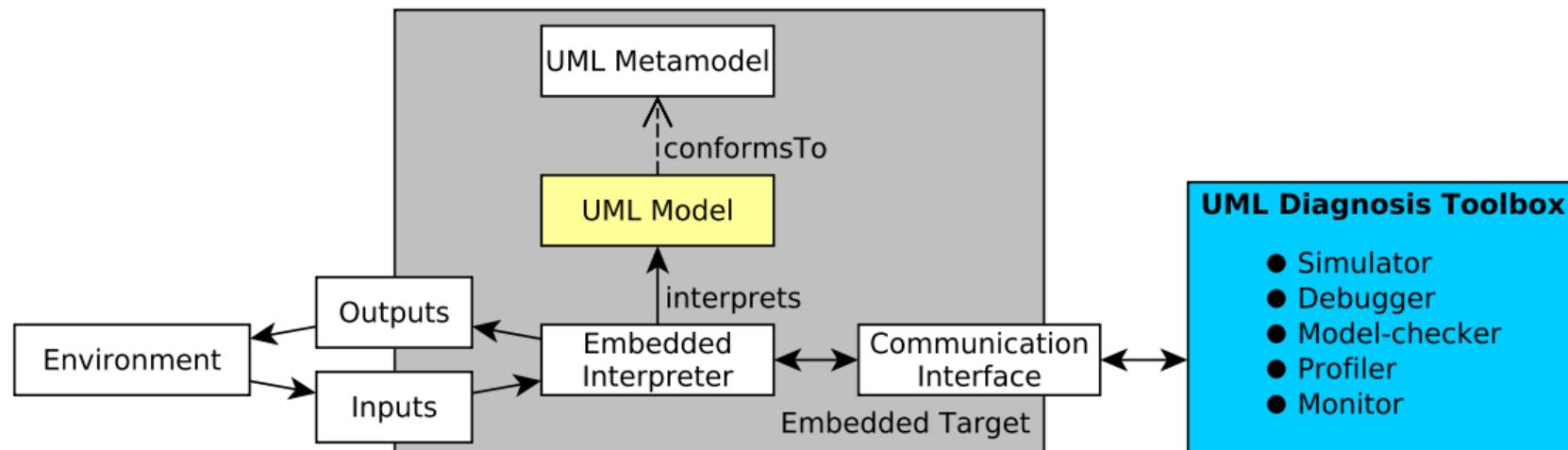
# Our Approach: A Unified Modeling Language Semantics



Other tools are able to execute and analyze models:

GEMOC Studio [Bousse et al., 2016], Moliz [Mayerhofer et al., 2012], Moka [Revol et al. 2018], GUML [Charfi et al, 2012], Unicomp [Ciccozzi, 2018], Mbeddr [Voelter et al., 2012], etc.

# Our Approach: A Unified Modeling Language Semantics



A single implementation of the language semantics for all activities: simulation, execution, and diagnosis.

# Results

## Simulation

- Trace-based simulation

## Execution

- On bare-metal (without operating system) embedded targets
- On desktop computers

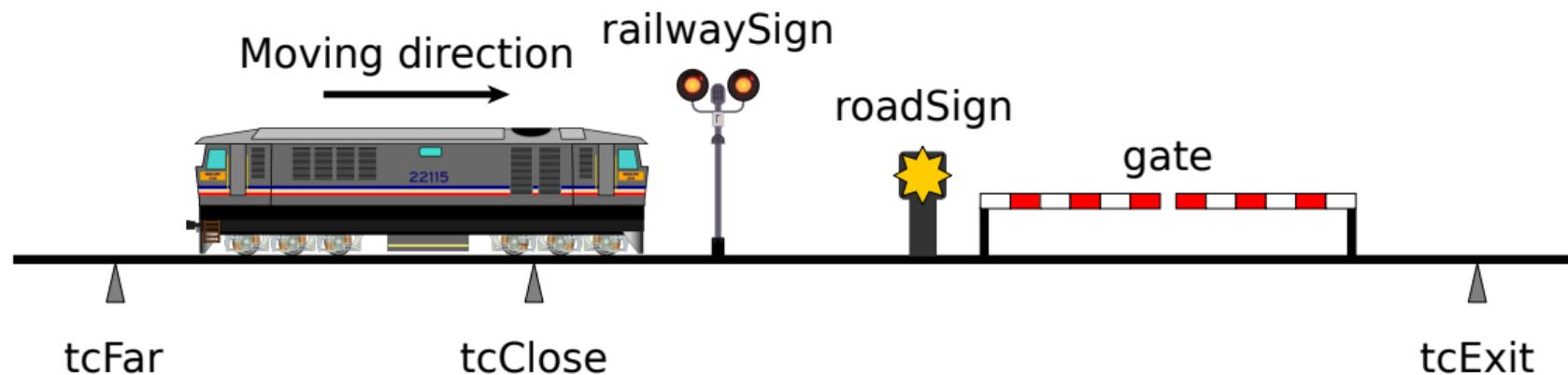
## Diagnosis

- State-space exploration
- Deadlock detection
- Model-checking of Linear Temporal Logic (LTL) properties

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# Level Crossing Overview



## Goal

Ensure safety during the passage of the train

# Level Crossing Model Requirements

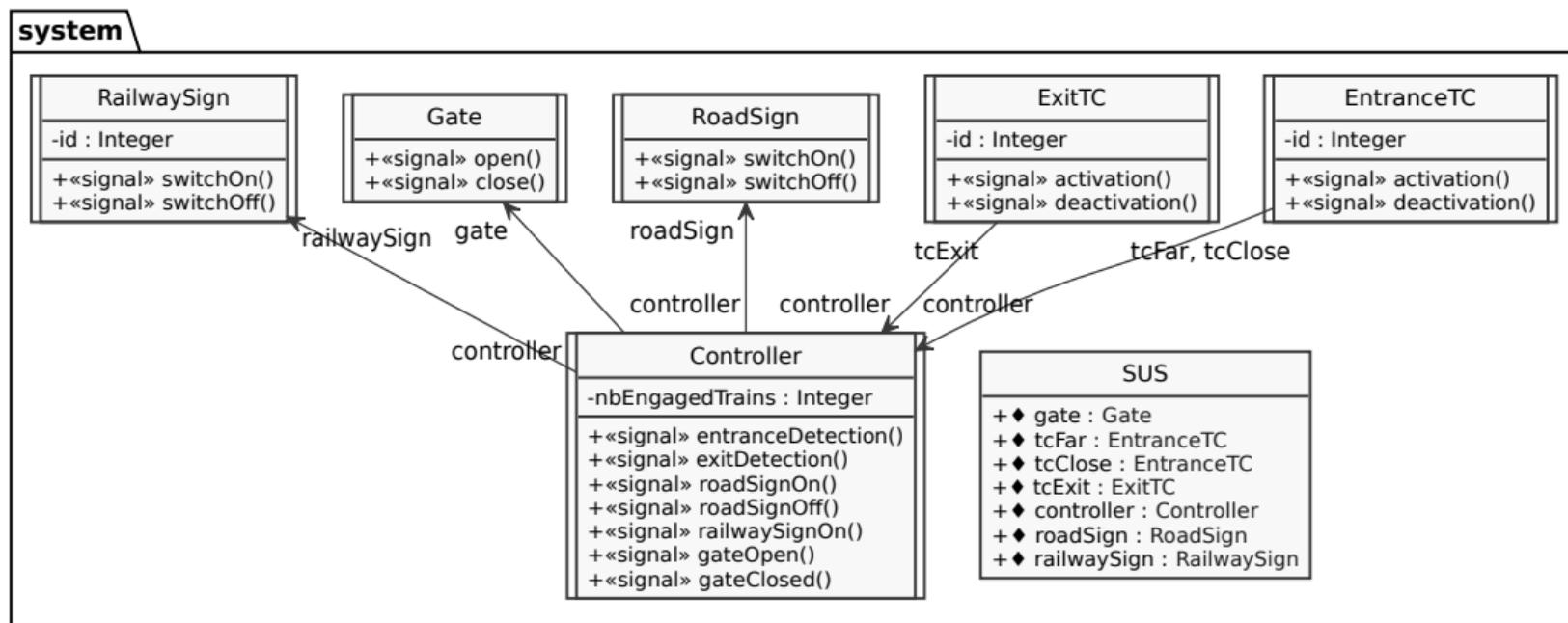
## Deadlock detection

- Ensuring that the model is deadlock free.

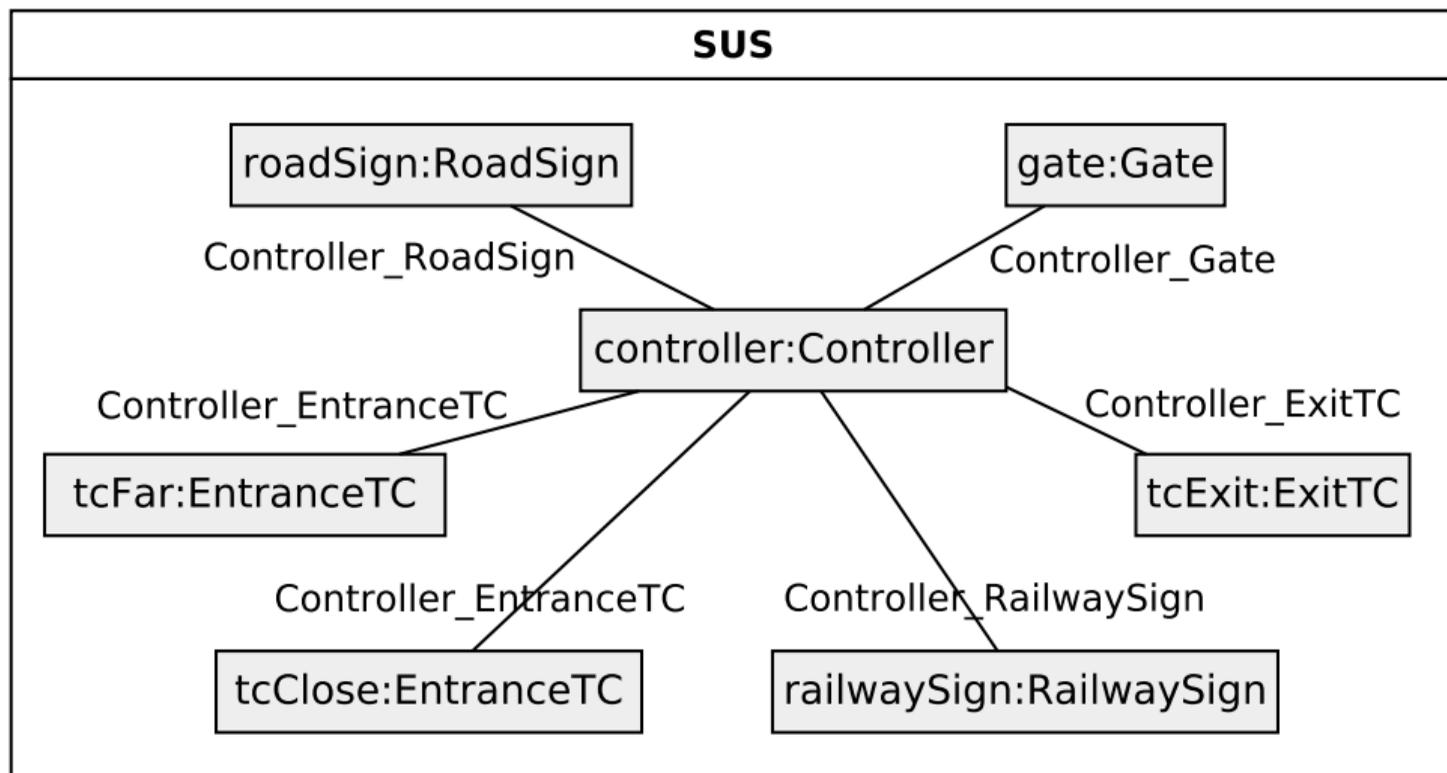
## System requirements

- 1 The Gate is closed when the Train is on the level crossing.
- 2 The light of the RoadSign is active when the Train is on the level crossing.
- 3 The Gate finally opens after being closed.
- 4 The light of the RoadSign is finally turn off after being activated.

# Level Crossing Model (Class Diagram)



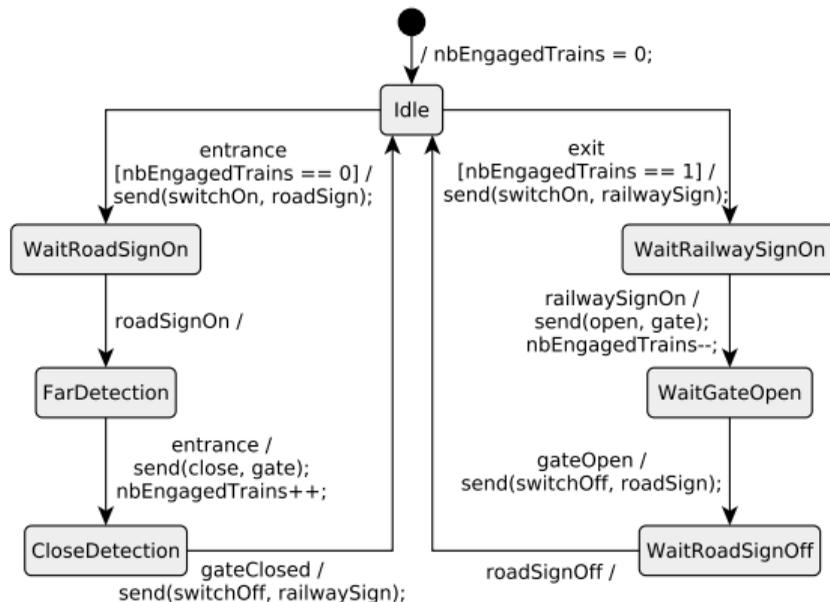
# Level Crossing Model (Composite Structure Diagram)



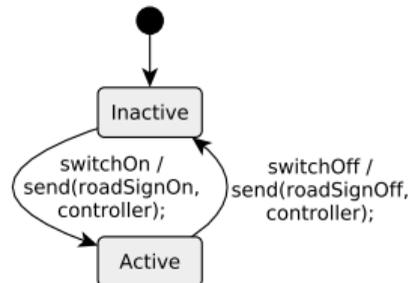
# Level Crossing Model (State Machines)



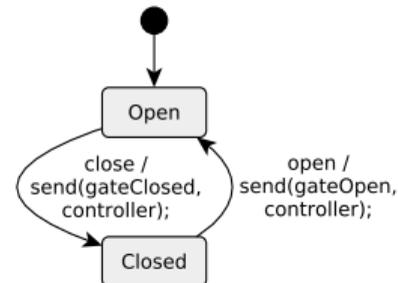
**Controller**



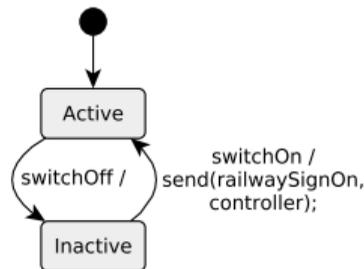
**RoadSign**



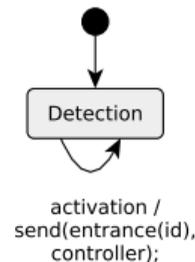
**Gate**



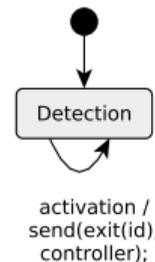
**RailwaySign**



**EntranceTC**



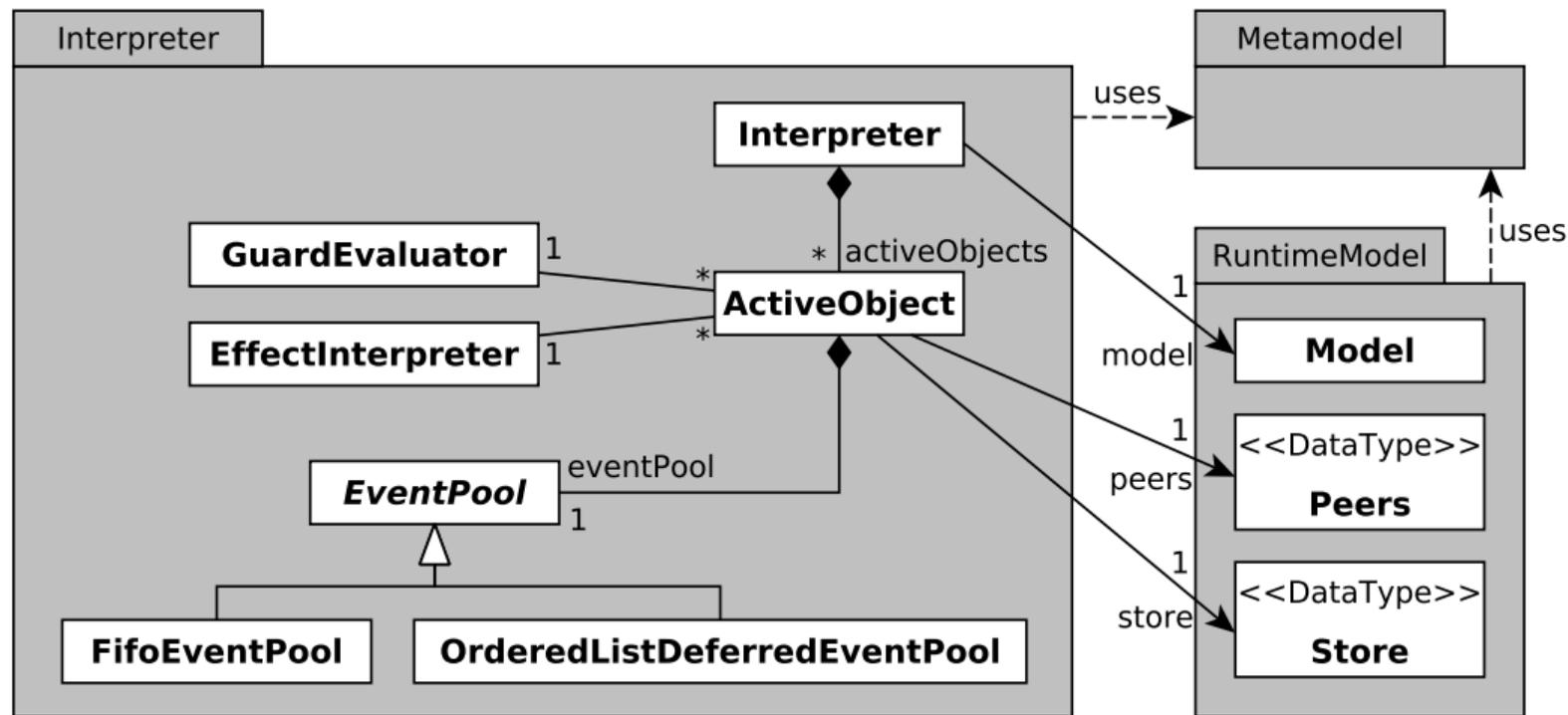
**ExitTC**



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## UML Interpreter Design

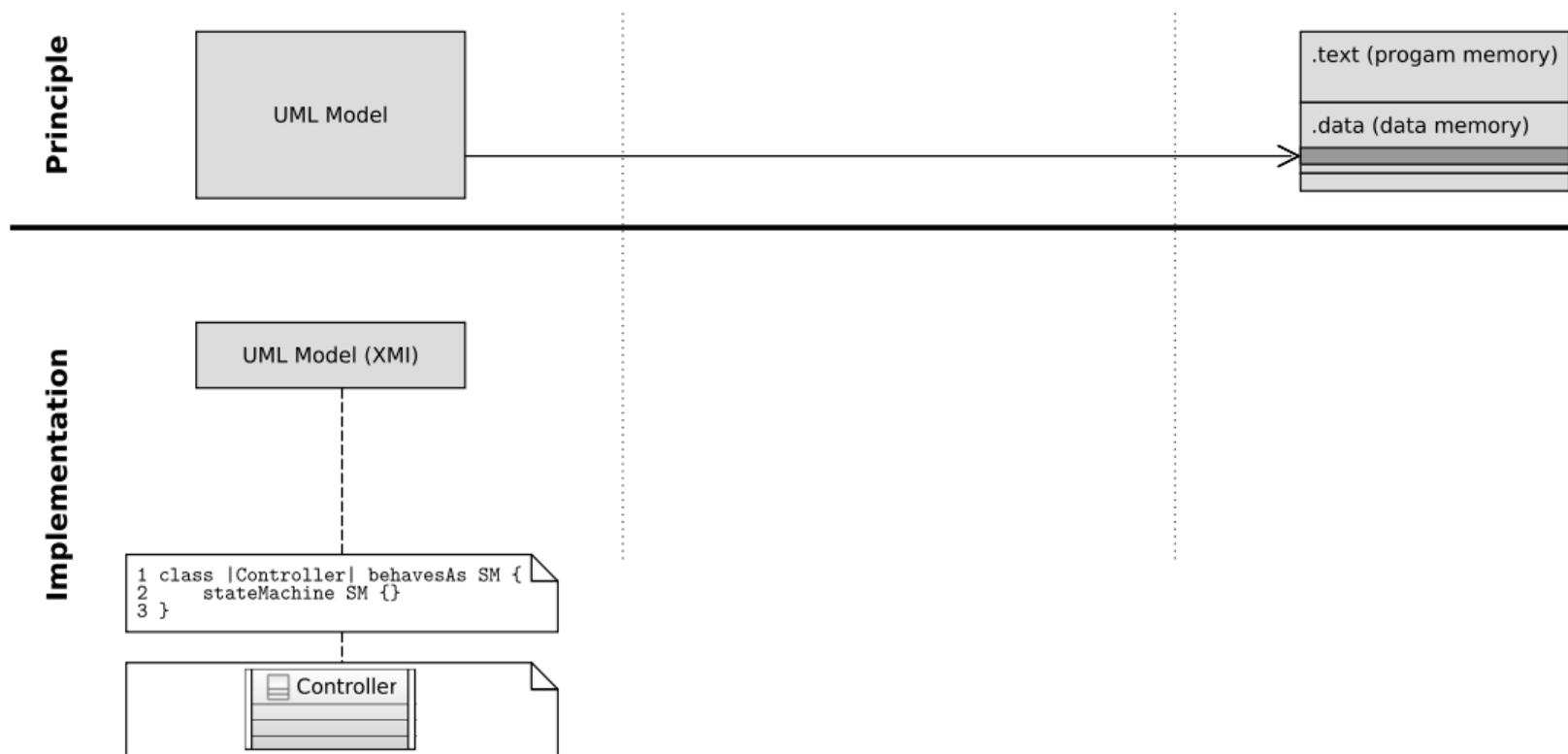


# Loading the Runtime Model at Compile-Time

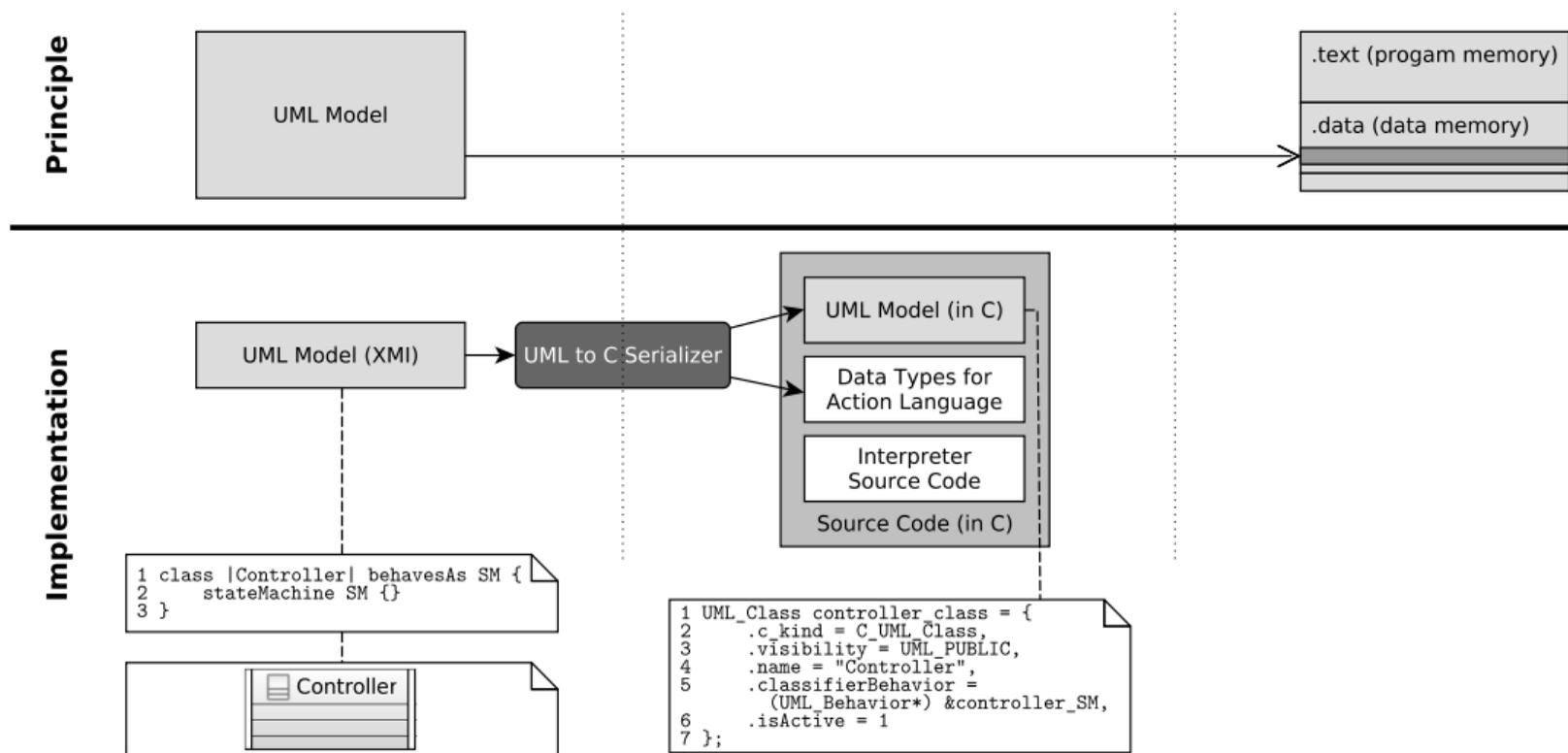
## Principle



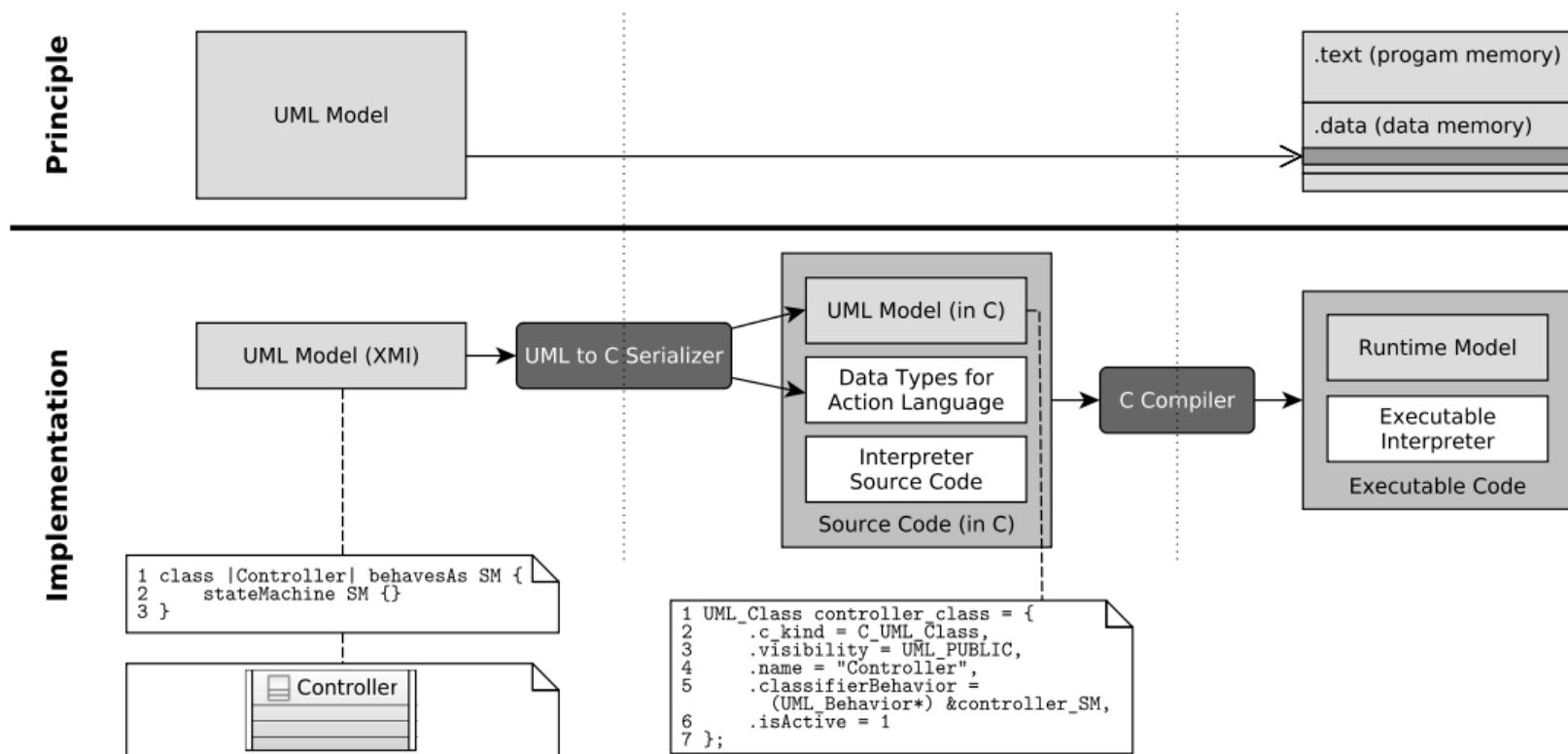
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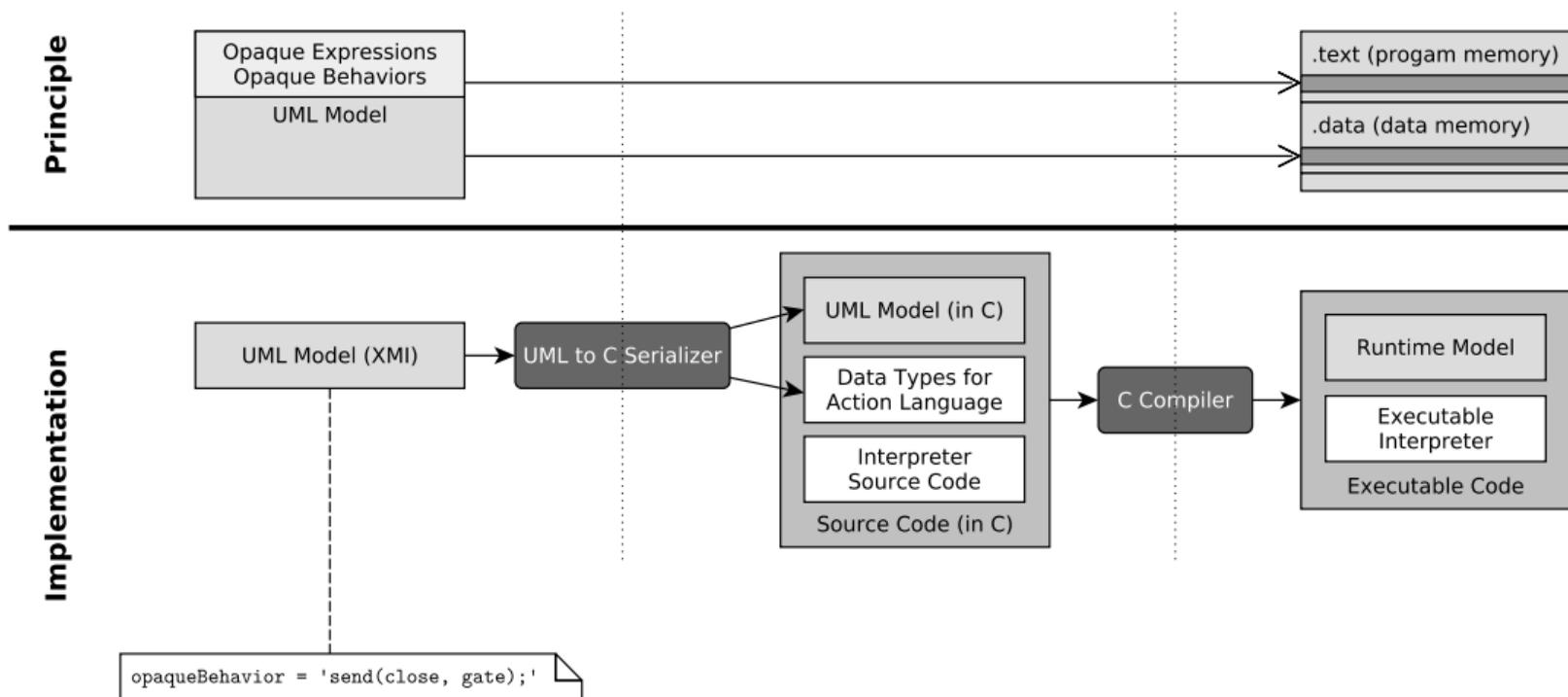
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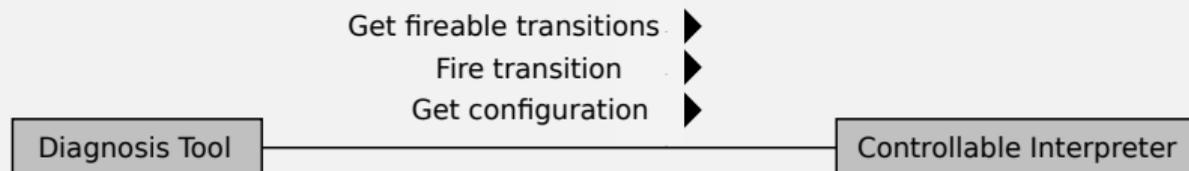
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# UML Model Diagnosis: Goals and Requirements

## Our goals

- Simulate the model

## Requirements to achieve these goals

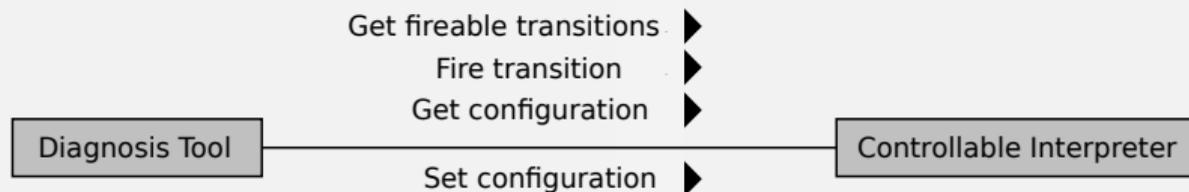


# UML Model Diagnosis: Goals and Requirements

## Our goals

- Simulate the model (with rollback for back-in-time simulation)
- Explore the model state-space
- Detect deadlocks

## Requirements to achieve these goals

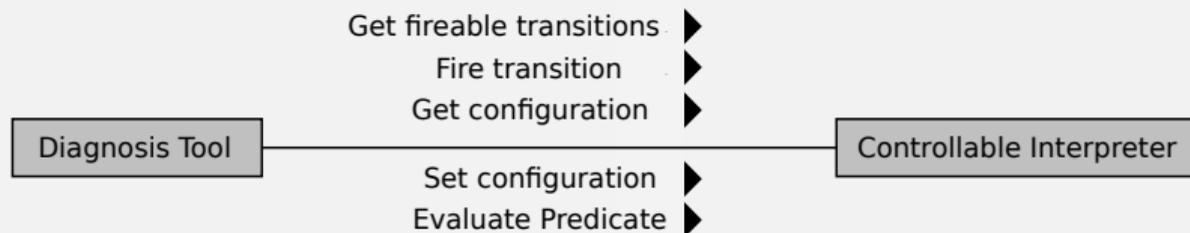


# UML Model Diagnosis: Goals and Requirements

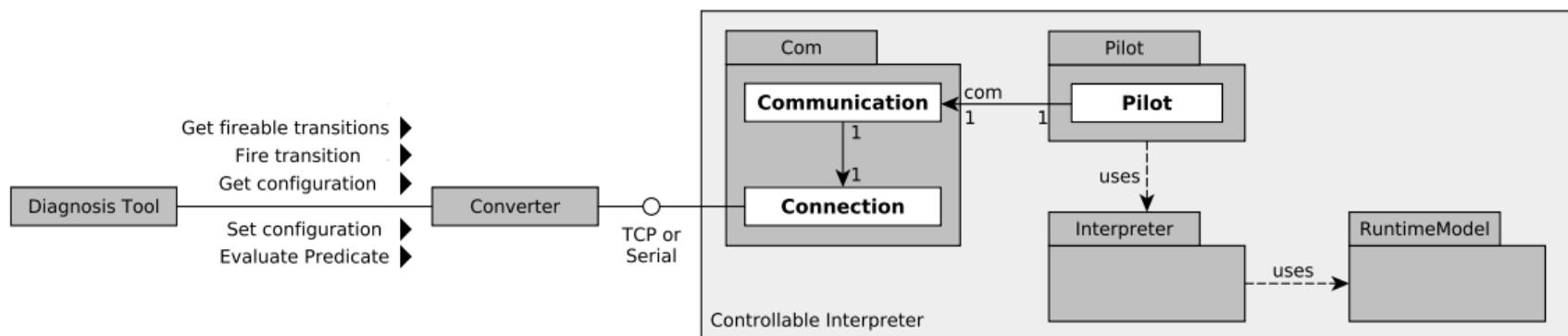
## Our goals

- Simulate the model (with rollback for back-in-time simulation)
- Explore the model state-space
- Detect deadlocks
- Verify formal properties via model-checking

## Requirements to achieve these goals



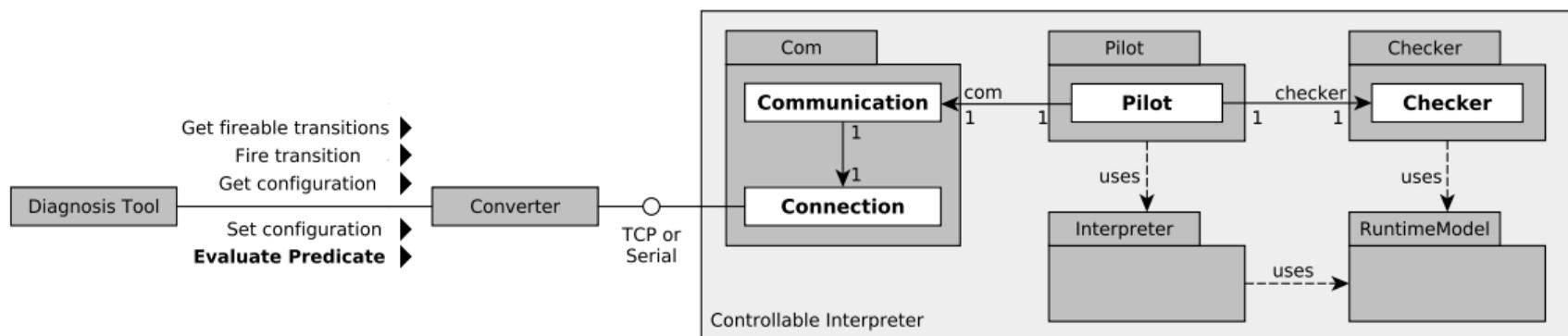
# Diagnosis Design



Design of an application layer protocol over:

- TCP connection
- Serial connection (e.g., UART, USB)

# Diagnosis Design



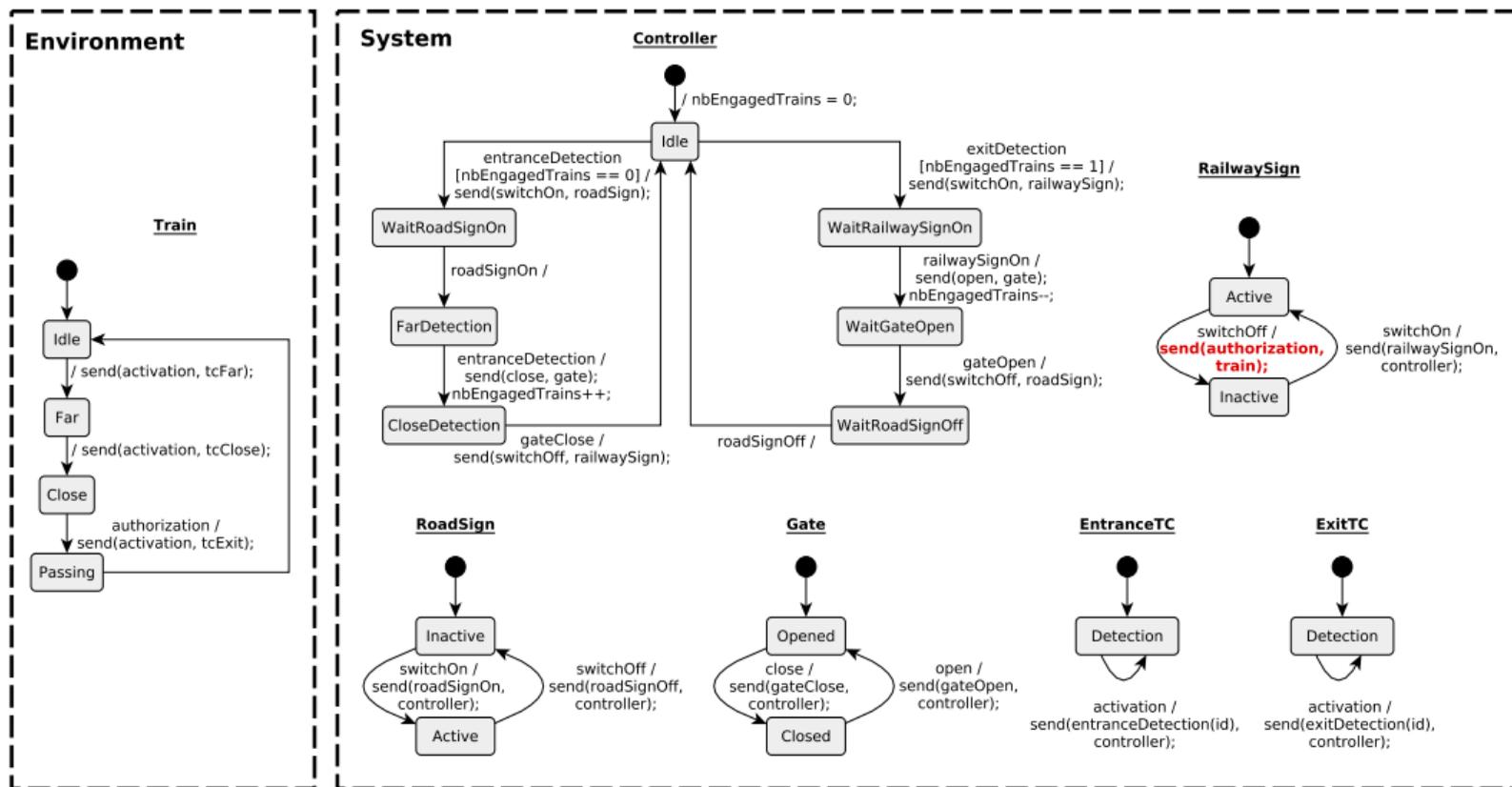
A formal property consists of:

- Atomic propositions (i.e., predicates related to model concepts)
  - Compiled into executable code by the converter
  - Evaluated by the controllable interpreter
- Logical operators used to link atomic propositions together
  - Evaluated by the diagnosis tool (model-checker)

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## Level Crossing Model Under Verification



# Model-Checking of the Level Crossing Model

## Expression of Properties into LTL

- 1 `[] !(trainIsPassing && gateIsOpen)`
- 2 `[] !(trainIsPassing && roadSignIsOff)`
- 3 `[] (gateIsClosed -> <> gateIsOpen)`
- 4 `[] (roadSignIsOn -> <> roadSignIsOff)`

# Model-Checking of the Level Crossing Model

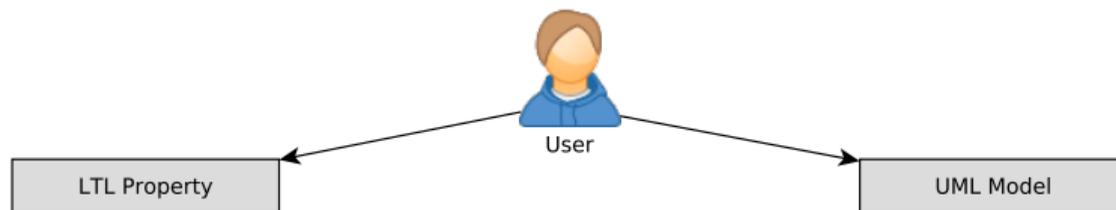
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## Expression of Atomic Propositions

- `trainIsPassing = |train.state == PASSING|`
- `gateIsClosed = |gate.state == CLOSED|`
- `gateIsOpen = |gate.state == OPEN|`
- `roadSignIsOn = |roadSign.state == ACTIVE|`
- `roadSignIsOff = |roadSign.state == INACTIVE|`

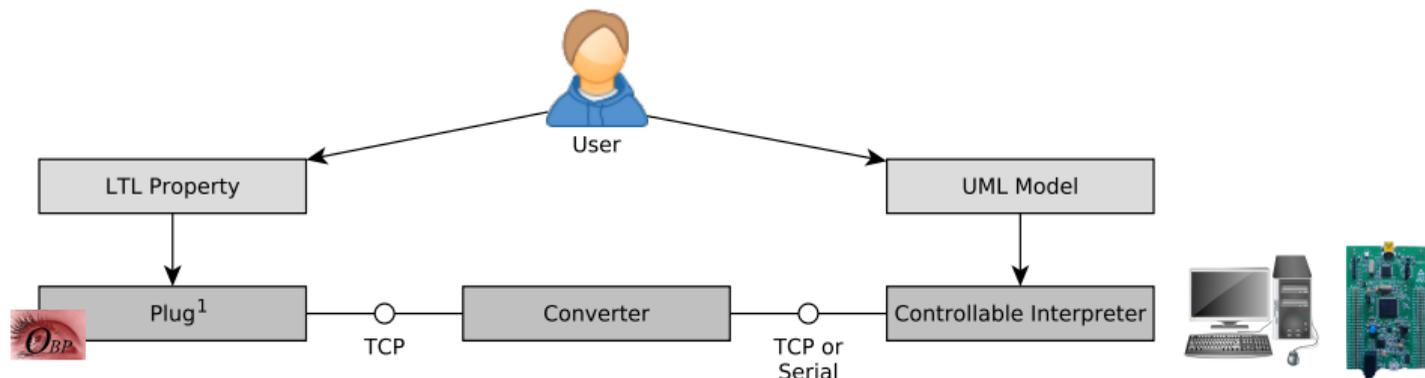
# Experiments



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<sup>1</sup><https://plug-obp.github.io/>

# Experiments



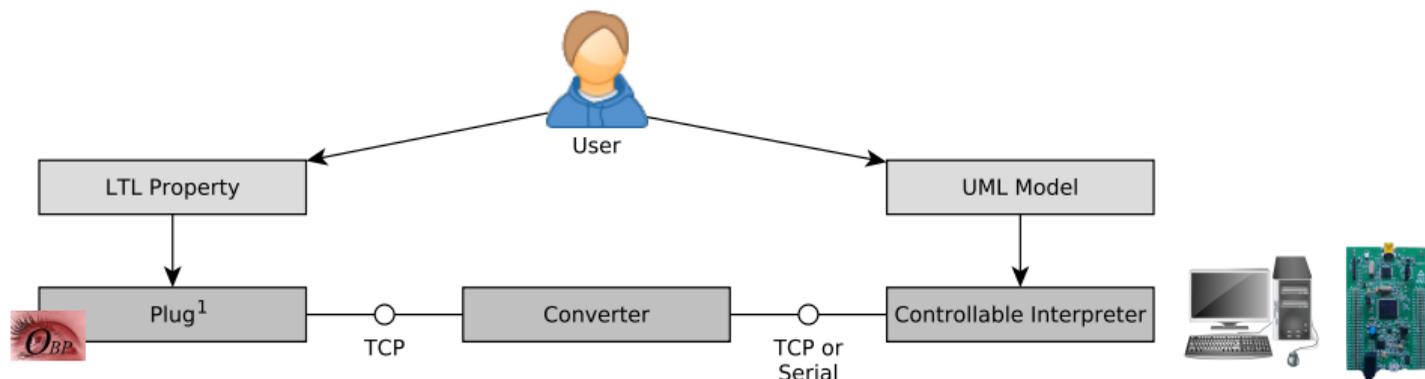
## Experiments

Diagnosis of the level-crossing model on:

- Desktop computer
- STM32 discovery

<sup>1</sup><https://plug-obp.github.io/>

# Experiments



## Experiments

Using the two implementations of the event pool

- the FIFO implementation that drops ignored events
- the ordered list implementation that defers ignored events

<sup>1</sup><https://plug-obp.github.io/>

## Results - Simulation

Analyze execution 'BFS Explorer'

[controller] WaitRoadSignOn -> FarDetection	9d203011
[train] Far -> Close	72f3478c

▼ controller

- cs = WaitRoadSignOn
- ▼ ep
  - nbEvents = 1
  - ▼ eventOccurred
    - ▼ eventOccurred[0]
      - signalEventId = roadSignOn\_SE

5adeaf8d x > ← a499572e x >

915d536c x >

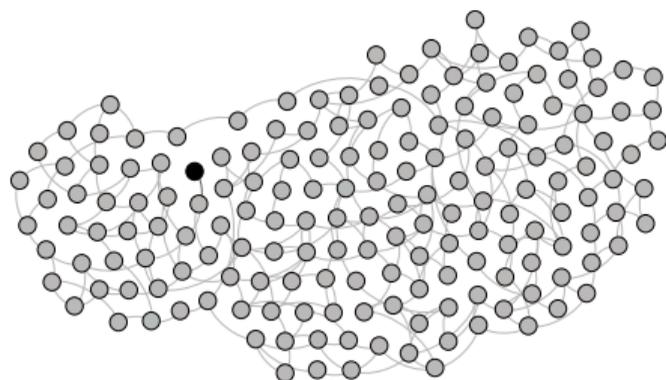
e162988e x > ← f0aa6632 x >

8a4e9c2b x > ← 22ee026a x >

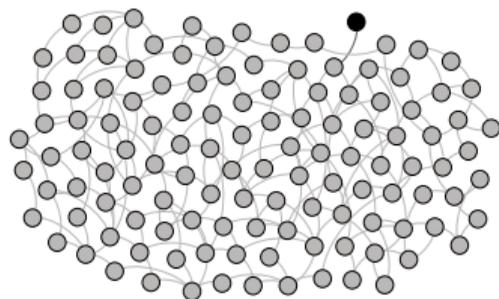
f49e9c50 x > ← 5ec48b8e x > ← d40943cc x >

## Results - State-space Exploration

	FIFO (drops)	OrderedList (defers)
Nb configurations	173	122
Nb transitions	276	209



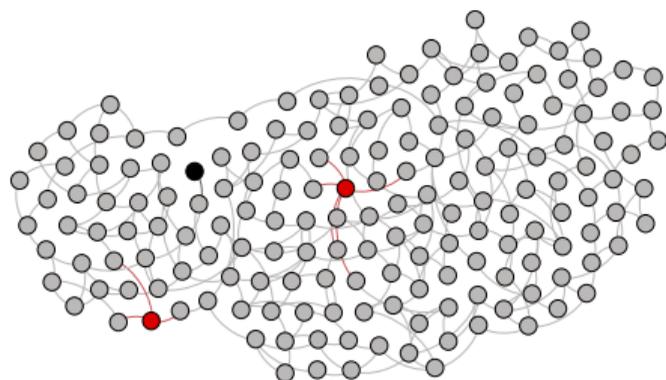
State-space graph with FIFO



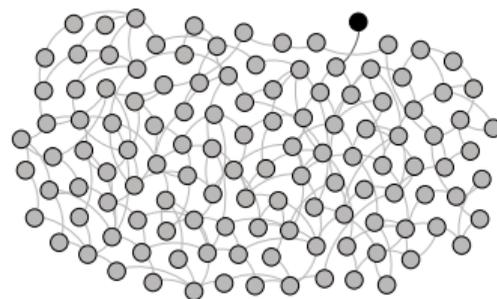
State-space graph with OrderedList

## Results - Deadlock Detection

	FIFO (drops)	OrderedList (defers)
Nb configurations	173	122
Nb transitions	276	209
Nb deadlocks	2	0



State-space graph with FIFO



State-space graph with OrderedList

## Results - LTL Model-checking

	FIFO (drops)	OrderedList (defers)
[] !(trainIsPassing && gateIsOpen)	✓	✓
[] !(trainIsPassing && roadSignIsOff)	✓	✓
[] (gateIsClosed -> <> gateIsOpen)	✓	✓
[] (roadSignIsOn -> <> roadSignIsOff)	✗	✓

✓: Property verified

✗: Property violated

## Execution performance

Verification of the 4 properties on a desktop computer<sup>1</sup> in 1.71 seconds<sup>1</sup>Intel® Core™ i7-8550U CPU at 1.80GHz with 4 cores, 16GB DDR4 2400MHz RAM, running a Linux OS

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# Conclusion

## Our contribution

- Use the same operational semantics implementation for execution and LTL verification
- What is checked during model diagnosis is what is executed at runtime

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<sup>1</sup>Preliminary study: <https://plug-obp.github.io/experiments/>

# Conclusion

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## Limitations

- No support for UML activities
- No evaluation of the resource overhead of the interpreter

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## Limitations

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## Perspectives

- Support multiple action languages (e.g., UML activities / Alf)
- Integrate the tool with UML modelers (e.g., Papyrus) <sup>1</sup>
- Apply this approach to other domain-specific languages (e.g., Capella in Eclipse PolarSys)

<sup>1</sup>Preliminary study: <https://plug-obp.github.io/experiments/>

Thank you for your attention



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